Redshift-space distortion systematics and Mitigations

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- Quick introduction to RSD.
- RSD modelling.
- List of potential systematics.
 - Including overview of current RSD constraints (heavily biased towards BOSS).

Quick introduction to RSD

The redshift of a galaxy has two velocity components which we can't distinguish (easily)

$$\vec{s} = \vec{r} \left(1 + \frac{u(\vec{r})}{r} \right).$$

On linear scales the effect is proportional to $\beta = \frac{f(z)}{b_1}$ with the growth rate

$$rac{d(\ln D(z))}{d(\ln a)} = f(z) pprox \Omega_m^\gamma(z),$$

where γ depends on the theory of gravity. So we can test the matter content of the Universe and/or the underlying gravity theory. Coherent/supercluster infall (Kaiser effect)

Random (thermal) motion



- Establish a connection between the galaxy density field and the matter density field (galaxy bias, *b*₁).
- Model the anisotropy due to RSD as suggested by Kaiser (1987), Cole et al. (1995), Peacock & Dodds (1996)

$$P_{
m lin}^{s}(k,\mu) = (b_{1} + f\mu^{2})^{2} P_{
m lin}(k) e^{-(k\sigma_{FoG}\mu)^{2}}$$

• The Alcock-Paczynski effect also introduces anisotropy

$$F(z) = (1+z)D_A(z)H(z)/c,$$

which has a different shape-dependence than RSD, if one has a large dynamic range.

• FoG are already a 10% effect by $s \sim 25h^{-1}$ Mpc [$k \sim 0.15$].

Modelling linear galaxy clustering



Percival & White (2008)

Most of the information is on small scales, so we have to understand non-linear physics:

- Non-linear matter clustering δ_m .
- Non-linear RSD (non-linear velocity field).
- Non-linear relation between δ_m and δ_g (bias).

There have been numerous approaches to model RSD in BOSS

- Gaussian streaming models (Reid et al. 2014, Samushia et al. 2016)
- Convolution Lagrangian Perturbation Theory (Satpathy et al. 2017)
- Kaiser + pert. inspired P_{real} (Sanchez et al. 2016)
- Renormalised PT model (Beutler et al. 2016, Gil-Marin et al. 2016)
- Distribution function model (Hand et al. 2017)
- EFT (in preparation)

PT approach for non-linear effects

Based on renormalized perturbation theory (Taruya et al. 2011, McDonald & Roy 2009, Saito et al. 2014)

$$\begin{split} P_{\mathrm{g}}(k,\mu) &= \exp\left\{-(fk\mu\sigma_{\mathrm{v}})^{2}\right\} \left[P_{\mathrm{g},\delta\delta}(k) \\ &+ 2f\mu^{2}P_{\mathrm{g},\delta\theta}(k) + f^{2}\mu^{4}P_{\theta\theta}(k) \\ &+ b_{1}^{3}A(k,\mu,\beta) + b_{1}^{4}B(k,\mu,\beta)\right], \end{split}$$

with

$$\begin{split} P_{\mathrm{g},\delta\delta}(k) &= b_{1}^{2}P_{\delta\delta}(k) + 2b_{2}b_{1}P_{b2,\delta}(k) + 2b_{s2}b_{1}P_{bs2,\delta}(k) \\ &+ 2b_{3\mathrm{nl}}b_{1}\sigma_{3}^{2}(k)P_{\mathrm{m}}^{\mathrm{L}}(k) + b_{2}^{2}P_{b22}(k) \\ &+ 2b_{2}b_{s2}P_{b2s2}(k) + b_{s2}^{2}P_{bs22}(k) + N, \\ P_{\mathrm{g},\delta\theta}(k) &= b_{1}P_{\delta\theta}(k) + b_{2}P_{b2,\theta}(k) + b_{s2}P_{bs2,\theta}(k) \\ &+ b_{3\mathrm{nl}}\sigma_{3}^{2}(k)P_{\mathrm{m}}^{\mathrm{lin}}(k), \end{split}$$

with 4 (6) free nuisance parameter

PT approach for non-linear effects



Beutler et al. (2014)

BOSS blind mock challenge



data by Jeremy Tinker



Alam et al. (2016)

Distribution function approach



- The model includes 9 (10) free nuisance parameters (based on the halo model).
- Including scales up to $k_{\rm max} = 0.4 h^{-1} {\rm Mpc}$ only reduces the error on $f\sigma_8$ by 15 30%.
- Including the bispectrum might help constraining the PT nuisance parameters (Gil-Marin et al. 2016).

Potential systematics

- Non-linear matter clustering δ_m .
- Non-linear RSD (non-linear velocity field).
- Non-linear relation between δ_m and δ_g (bias).
- Survey geometry (window function).
- Approximations in N-point estimators (wide-angle effects etc.).
- Cosmological/theoretical assumptions (e.g. neutrino mass).
- The baryon-dark matter relative velocity (Tseliakhovich & Hirata 2010).
- Fibre collisions or in general any correlation of failure rate with the underlying density field.
- Galaxy tidal alignment (Martens et al. 2018), correlations of galaxy density and stellar density (Ross et al. 2012) or in general any correlation of selection probability with the underlying density field.
- Galaxy assembly bias.
- Non-Gaussian likelihood distributions (Hahn et al. 2018).
- The connection between the galaxy density and the matter density might be non-local (non-local bias).

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Survey geometry (window function) in BOSS



Hand, Seljak, Beutler & Vlah (2017)

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Approximations in N-point estimators

The Fourier-space FFT-based estimators use an approximation

$$P_{\ell}(k) = (2\ell+1) \int \frac{d\Omega_k}{4\pi} \int d\vec{s}_1 d\vec{s}_2 \delta(\vec{s}_1) \delta(\vec{s}_2) e^{-i\vec{k}\cdot\vec{s}} \mathcal{L}_{\ell}(\hat{k}\cdot\hat{s}_1),$$

which breaks the symmetry of the pair and introduces wide-angle effects.



Castorina & White (2018)

Approximations in N-point estimators (preliminary)



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Based on Yoo & Seljak (2011), Schmidt (2015) & Blazek et al. (2014)

$$\begin{split} P_{g}(k,\mu) &= P_{\mathrm{g,NL}}(k,\mu) + b_{v^{2}} \Big[b_{1} P_{\delta|v^{2}}(k) + b_{2} P_{\delta^{2}|v^{2}}(k) \\ &+ b_{s} P_{s^{2}|v^{2}}(k) + b_{v^{2}} P_{v^{2}|v^{2}}(k) \Big] \\ &+ b_{1} b_{v^{2}} P_{\mathrm{adv}|\delta}(k) + 2 b_{1} b_{\delta}^{\mathrm{bc}} P_{\delta|\delta_{\mathrm{bc}}} + 2 b_{1} b_{\theta}^{\mathrm{bc}} P_{\delta|\theta_{\mathrm{bc}}} \\ &- 2 f \mu^{2} \Big[b_{v^{2}} \left(b_{1} P_{\delta|v^{2}v_{\parallel}}(k) + P_{\mathrm{adv}|v_{\parallel}}(k) \right) \\ &- b_{\theta}^{\mathrm{bc}} P_{\delta|\theta_{\mathrm{bc}}} + b_{\delta}^{\mathrm{bc}} P_{\delta|\delta_{\mathrm{bc}}} \\ &+ b_{v^{2}} \left(P_{v^{2}|v_{\parallel}}(k) + P_{v^{2}|\delta v_{\parallel}}(k) \right) \Big] \\ &+ f^{2} \mu^{4} b_{v^{2}} P_{v_{\parallel}|v^{2}v_{\parallel}}(k) \\ &- f^{2} \mu^{2} b_{v^{2}} \left[l_{1}(k) + \mu^{2} l_{2}(k) \right], \end{split}$$

Beutler, Vlah & Seljak (2016)



Beutler, Vlah & Seljak (2016)



Schmidt & Beutler (2017)

BOSS, 68% (95%) confidence levels:

- $b_{v^2} = 0.012 \pm 0.015 (\pm 0.031)$ (see also Slepian et al. 2016)
- $b_{\delta}^{\rm bc} = -1.0 \pm 2.5 (\pm 6.2)$

•
$$b_{ heta}^{
m bc} = -114 \pm 55(\pm 175)$$

- $b_{
 m drag} = 140 \pm 1700 (\pm 4500)$
- $b_{\rm drag,bc} = -10 \pm 10 (^{+51}_{-28})$



Given these limits, potential shifts in the BAO measurements of BOSS are constrained to 0.53σ , 0.50σ and 0.22σ for $D_A(z)$, H(z) and $f\sigma_8$, respectively

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Observational systematics in BOSS



Reid et al. (2014), Hahn et al. (2016)

Observational systematics in DESI



Bianchi et al. (2017)

After 1 DESI pass (completeness 23%, worst case scenario)

Observational systematics in DESI



Bianchi et al. (2017)

After 4 DESI passes (completeness 80%, final DESI dataset)

O Modelling systematics are best handled by blind mock challenges.

- This is becoming standard in DES/BOSS/DESI.
- A huge amount of work!
- Observational systematics are best handled by correlating all aspects which go into target selection or observation (e.g. seeing condition etc.).

We can just try to model galaxy surveys using N-body simulations rather than PT:

- Starting redshift, force accuracy and softening, time stepping, box size, number of particles etc.
- Running a new simulation for each MCMC step or using emulators.
- How to go from dark matter to galaxies? HOD, abundance matching... big uncertainties or many parameters.
- Observational systematics like fibre collisions or instrumental effects can be included at the level of the density field.

Precision of N-body simulations



Schneider et al. (2016)

Forward modelling approach



Forward modelling approach in BOSS



- Marginalises over HOD parameters.
- Incorporates fibre collisions using the BOSS tiling algorithm.
- Does not yet marginalised over cosmological parameters.

Forward modelling approach in BOSS



This approach improves the constraints by a factor of ~ 2.5 compared to the PT based analysis $f\sigma_8 = 0.450 \pm 0.011$.

Look into the future



Beutler et al. (2012), Howlett et al. (2015), Blake et al. (2012), Alam et al. (2016)



Beutler et al. (2012), Howlett et al. (2015), Blake et al. (2012), Alam et al. (2016), Font-Ribera et al. (2015)



Beutler et al. (2012), Howlett et al. (2015), Blake et al. (2012), Alam et al. (2016), Font-Ribera et al. (2015)



Beutler et al. (2012), Howlett et al. (2015), Blake et al. (2012), Alam et al. (2016), Font-Ribera et al. (2015), Majerotto et al. (2012)



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- 2 Survey incompleteness (and correlations with δ) is going to be a bigger issue in DESI/Euclid compared to BOSS.



- O Modelling systematics can be handled using PT and by calibration against N-body simulations → blind mock challenges
- 2 Survey incompleteness (and correlations with δ) is going to be a bigger issue in DESI/Euclid compared to BOSS.
- Forward modelling can reduce the number of nuisance parameters connected non-linear δ_m .